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Version 1:

- Initial release

Version 1.1:

- Overhauled destination B to reflect new design
- Added limit switch component used in dest. B
- Fixed incorrect water location with respect to the ramp, previously the water did not line up with the bottom edge of the ramp as intended.
- Added rout grooves under hinge of dest. B to reduce friction from contact w/ the field.
- Added LED holder .STL file for 3D printing of the LED holders used to house the Indicator LEDs
- Added location of Laser sensor that will detect when a robot has successfully crossed the gangplank
- Added extra PDF files describing destination B assembly
- Added more images with better and more detailed views of different parts of the field